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Therefore it seems quite urgent to provide Reviews of Nonlinear Dynamics and Complexity where researchers or newcomers to the field can find the most important recent results, described in a fashion which breaks the barriers between the disciplines.

The response curves and the discussion of the previous section therefore still apply after taking into account all the quadratic and cubic nonlinear terms. For example, Kozinsky et al. Note that due to the different signs of the various contributions to the effective nonlinear parameters, one could actually cause the cubic terms to vanish, altering the response in a fundamental way. Instead of applying an external force that acts directly on the resonator, one modulates one or more of its physical parameters as a function of time, which in turn modulates the normal frequency of the resonator. This is what happens on a swing, where the up-and-down motion of the center of mass of the swinging child effectively changes the length of the 1. The most effective way to swing is to move the center of mass up-and-down twice in every period of oscillation, but one can also swing by moving up-and-down at slower rates, namely once every n th multiple of half a period, for any integer n . Above this threshold, the amplitude of the motion grows until it is saturated by nonlinear effects. The simplest, and probably the one most commonly used in the micron scale, is to use an external electrode that can induce an external potential that, if modulated in time, changes the effective spring constant of the resonator [15, 18, 19, 31, 55, 56]. Alternatively, one may generate motion in the clamps holding a doubly-clamped beam by its ends, as shown for example in Fig. These methods allow one to modulate the tension in the beam directly and thus modulate its normal frequency. More recently, Masmanidis et al. Only a minor change is required in our equation of the driven damped Duffing resonator to accommodate this new situation, namely the addition of a modulation of the linear spring constant. A metallic wire that runs along the external suspended segments of the H-device carries alternating current in opposite directions, thus applying opposite Lorentz forces that induce a time-varying compression of the central segment. This modulates the tension in the central segment, thus varying its normal frequency. Image courtesy of Michael Roukes. The term proportional to H on the left hand side is the external drive that modulates the spring constant, giving a term that is proportional to the displacement x as well as to the strength of the drive $\hat{\epsilon}$ ” this is the parametric drive. The new secular term, appearing on the right-hand side of Eq. We begin by assuming that the drive is small enough so that the magnitude of the response remains small and the nonlinear terms in Eq. Substituting this into Eq. Physically this means that the maximum of the signal occurs a quarter of a pump cycle after a maximum of the pump. This situation is discussed in the next section. A noise signal on the right-hand side of the equation of motion 1.

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